# NORMAL GAIT

## FUNDAMENTALS OF BIOMECHANICS & EXERCISE THERAPY:-



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### **DEFINITION:-**

- Human gait may be **define as** " the <u>translatory progression</u> of the human body as a whole, <u>produced</u> by coordinated, rotatory movements of the body segments" is known as <u>gait or human</u> <u>locomotion</u>
- Gait is the medical term to describe <u>human locomotion</u>, or the way that we walk.
- Every individual has a <u>unique gait pattern</u>.

### Normal Gait:-

Series of rhythmical, alternating <u>movements</u> of the trunk & limbs which result in the forward progression of the center of gravity & the body.

Fundamental Purposes of gait:-

- Support of the <u>HAT</u>.
- Maintenance of <u>upright posture & balance</u> of the body.
- Achieve <u>safe</u> ground <u>clearance</u> & a gentle heel or toe <u>landing</u>.
- <u>Generation of mechanical energy</u> to maintain the present forward velocity or to increase the <u>forward velocity</u>.
- <u>Absorption</u> of mechanical energy for shock absorption & stability or to decrease the forward velocity of the body.

### Prerequisites of gait:-

### There are (4) major criteria essential to walking.

- Equilibrium: The ability to assume an upright posture and maintain balance.
- Locomotion: The ability to initiate and maintain rhythmic stepping
- **Musculoskeletal Integrity:** Normal bone, joint, and muscle function

### • Neurological Control:

Must receive and send messages telling the body how and when to move. (visual, vestibular, auditory, sensori-motor input)

• Forces for gait:

Muscular force.

Gravitational force.

Forces of momentum.

Floor reaction force.

### Gait cycle

- Describe the <u>complex activity of walking</u>, or our gait pattern.
- This cycle describes the <u>motions</u> from initial placement of the supporting heel on the ground to when the same heel contacts the ground for a second time.
- **Defined** as the <u>period of time</u> from one heel strike to the next heel strike of the same limb.
- Gait Cycle =
  - Single sequence of functions by one limb
  - Begins when reference foot contacts the ground
  - Ends with subsequent floor contact of the same foot on the ground.

One gait cycle consists of two phases

### 1) STANCE PHASE (60%)

### 2) SWING PHASE (40%)



### **EVENTS IN STANCE PHASE:-**

- Heel strike
- Foot flat
- Mid-stance
- Heel off
- Toe off

### **EVENTS IN SWING PHASE:-**

- Acceleration
- Mid swing
- Deceleration



### A. Stance phase:

- 1. Heel contact: 'Initial contact'
- 2. Foot-flat: 'Loading response', initial contact of forefoot w. ground
- 3. Midstance: greater trochanter in alignment w. vertical bisector of foot
- 4. Heel-off: 'Terminal stance'
- 5. Toe-off: 'Pre-swing'



The three subphases of swing phase.

### B. Swing phase:

- 1. Acceleration: 'Initial swing'
- 2. Midswing: Swinging limb overtakes the limb in stance
- 3. Deceleration: 'Terminal swing'

### Stance Phase:-

• Heel strike phase:

Begins with initial contact & ends with foot flat

It is beginning of the stance phase when the heel contacts the ground.

• Foot flat:

It occurs immediately following heel strike

It is the point at which the foot fully contacts the floor

• Mid stance:

It is the point at which the body passes directly over the supporting extremity.

• Heel off:

The point following mid-stance at which time the heel of the reference extremity leaves the ground.

• Toe off:

The point following heel off when only the toe of the reference extremity is in contact with the ground.

### Swing Phase:-

### • Acceleration phase:

It begins once the toe leaves the ground & continues until mid- swing, or the point at which the swinging extremity is directly under the body.

### • <u>Mid-swing:</u>

It occurs approx when the extremity passes directly beneath the body, or from the end of acceleration to the beginning of deceleration

### • <u>Deceleration:</u>

It occurs after mid-swing when limb is decelerating in preparation for heel strike.

# Right heal Bight heal Foct flat Midstance

# **STANCE PHASE**



# **SWING PHASE**

### GAIT TERMINOLOGIES

### **Temporal Variable**

- Stance time
- Single limb & double limb time
- Swing time
- Stride & Step time
- Cadence
- Walking Speed

### **Distance Variable**

- Stride length
- Step length
- Step Width
- Degree of toe-out

